



- 8 Inputs 24V, $R_i = 5k\Omega$
- 8 Output Relays (Tyco PCN-124D3MHZ)
- Status indicators for each Input and Output
- RS232 connection via DSUB9-Socket (DCE)
- Supply Voltage (Logic) 8 .. 30 VDC
- Supply Voltage (Relays) 18 .. 30 VDC
- Dimensions: 120mm(D) x 22,5mm(W) x 100mm(H)
- Pluggable cage clamp terminals max. 0,5mm²
- DIN Rail mounting



Safety notes

This product is not fail-safe and should not be used in life-supporting systems and other applications which are critical for safety, without a new risk assessment and evaluation of the conformity! If the module is intended to be installed into a machine or a system, for which the EC machinery directive 98/37 or its amendment is valid, it is necessary to make sure that the product, after its application, complies with all relevant regulations!

Application

The interface component offers a simple method to control up to eight digital inputs and outputs through a serial RS232 communication port. Since inputs and outputs are separated from the remaining circuitry by optical couplers, signals of industrial controls can be easily connected to a PC or a terminal or other devices with serial communication ports. The digital inputs are designed for 24VDC. The outputs are potential free normally open contacts, by Tyco PCN124D3MHZ, with a switching capacity of 3A@30VDC respectively 3A@250VAC. Logic and decoupled outputs may be separately powered. The component is easy-to-mount on a 35 mm-DIN rail. The electrical connection is made by pluggable cage clamp terminals.

Function

Serial to parallel conversion and vice versa will be performed by a PIC16F877 (MicroChip). On a simple command, the standard firmware reads the inputs and outputs, and transfers the data to the PC or to a corresponding device. If parameters are transferred with the command, the outputs will be set accordingly. Additionally, an automated scan takes place at an interval of 100ms. If there is a difference compared to the last status, a notification will be sent automatically. Thus it is possible to easily detect changes on the inputs. If special relations between inputs to outputs are required, it is possible to deliver a customized firmware.

Operation

Start-up is quite simple. After connecting the supply voltage (logic) the module is ready for use. For applications where no outputs are required, the supply voltage (load) can be omitted. The communication with the module is realized by means of simple ASCII code commands at a transfer rate of 9600 bauds (9600,8,N,1) and can be easily executed out of any application, through any serial communication port. It is not necessary to use special drivers to operate the module. For checking the communication, any terminal program can be used. Ready status is indicated by two LEDs. Whereas the first LED indicates the applied operating voltage, the second LED indicates the heart-beat, which is regularly controlled by the processor. The receipt of a command is indicated by one more LED..

Operation as MFR module

For operation as a multifunction relay and programming the different modes, you need to install the necessary configuration software. The latest version may be download from <http://zeb-automation.de/de2/>. It is free of charge. Using this tool, it is possible to assign special functions to each of the eight channels. As soon as it is configured, the software is no longer needed to operate the module. This tool also allows updating the firmware of the MFR module.

Data communication

Command	Parameter	Function	Return Value
'X'	none	Reset	'XSP11R' CR
'I'	none	Reads input bits	'I' I.7-4 I.3-0 CR
'O'	none	Reads output bits	'O' O.7-4 O.3-0 CR
'O'	'@' + bit7..4 '@' + bit3..0	Sets the output bits 7..0	none
others **	With or without	No Function	'?' CR

Command line: Command [Parameter] CR(0Dh)

** There are further commands assigned for MFR functions. They return other information! Refer to *mfr_api.pdf*.

Examples:

The command linez 'OAC' followed by CR(0Dh) is setting the output bits 4,1,0 to active.
The return value 'I@A' followed by CR(0Dh) indicates a signal at input bit 0.

Character	Bit 7/3	Bit 6/2	Bit 5/1	Bit 4/0	Character	Bit 7/3	Bit 6/2	Bit 5/1	Bit 4/0
@	0	0	0	0	H	1	0	0	0
A	0	0	0	1	I	1	0	0	1
B	0	0	1	0	J	1	0	1	0
C	0	0	1	1	K	1	0	1	1
D	0	1	0	0	L	1	1	0	0
E	0	1	0	1	M	1	1	0	1
F	0	1	1	0	N	1	1	1	0
G	0	1	1	1	O	1	1	1	1

Pin assignments

Signal	Pin		Pin	Signal																								
		Terminal strips The left columns designate the connections of the lower terminal strip from rear to front, whereas the right columns designate the connections of the upper terminal strip from rear to front, if device is mounted in upright position.	Ub+	Supply Voltage (Logic) 8 .. 30 VDC																								
			Ub-																									
			Us+	Supply Voltage (Relays) 18 .. 30 VDC																								
			Us-																									
Isolated Input Bit 0	I0+ I0-		O0 O0	Output Bit 0																								
Isolated Input Bit 1	I1+ I1-		O1 O1	Output Bit 1																								
Isolated Input Bit 2	I2+ I2-	<table><tr><th colspan="2">DSub9-Socket (DCE)</th></tr><tr><th>Pin</th><th>Signal</th></tr><tr><td>1</td><td>Data Carrier Detect (NC)</td></tr><tr><td>2</td><td>* Transmitted Data</td></tr><tr><td>3</td><td>* Received Data</td></tr><tr><td>4</td><td>DTE Ready</td></tr><tr><td>5</td><td>* Signal Ground</td></tr><tr><td>6</td><td>DCE Ready</td></tr><tr><td>7</td><td>Clear to Send</td></tr><tr><td>8</td><td>Ready to Send</td></tr><tr><td>9</td><td>Ring Indicator (NC)</td></tr><tr><td colspan="2">* necessary connections</td></tr></table>	DSub9-Socket (DCE)		Pin	Signal	1	Data Carrier Detect (NC)	2	* Transmitted Data	3	* Received Data	4	DTE Ready	5	* Signal Ground	6	DCE Ready	7	Clear to Send	8	Ready to Send	9	Ring Indicator (NC)	* necessary connections		O2 O2	Output Bit 2
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Isolated Input Bit 3	I3+ I3-	O3 O3	Output Bit 3																									
Isolated Input Bit 4	I4+ I4-	O4 O4	Output Bit 4																									
Isolated Input Bit 5	I5+ I5-	O5 O5	Output Bit 5																									
Isolated Input Bit 6	I6+ I6-	O6 O6	Output Bit 6																									
Isolated InputBit 7	I7+ I7-	O7 O7	Output Bit 7																									

MFR Functions

Beside the application as an I/O interface connected to a serial communication RS232 port, it is possible to use the module as a multifunction relay. Using a corresponding configuration it is possible to assign to each of the 8 channels a different function. The required programming will be performed by means of the configuration software **MFRSETUP** (currently available for Windows applications). The latest version may be download from <http://zeb-automation.de/de2/>. As soon as the module is configured, the software is no longer needed to operate the device. Programming the appropriate parameters is self-explanatory to the greatest possible extent. Additionally there is a comprehensive Windows help, also available as a separate file **MFRHELP**.

Simple Interface (Factory setting on delivery)	The MFR functions are disabled. Inputs are read and outputs are controlled by an external unit via the serial communication port.
Direct	Time functions are disabled. The output follows the input.
Switching-on delay	Applying a voltage to the input, the output will be active after the configured delay. With removing the input voltage the output will be immediately inactive.
Switching-off delay	Applying a voltage to the input, the output will be active immediately. With removing the input voltage, the output will be inactive after the configured delay.
Clock Pulse/Pause	The output acts as a flasher. Either free-running or controlled via the corresponding input. The duration of pulse and pause is configurable.
Clock Pulse/Cycle	The output acts as a pulse generator. Either free-running or controlled via the corresponding input. The duration of pulse and cycle is configurable.
Switching-on wipe pulse, Switching-off wipe pulse	The output generates a single pulse of configurable width, independent from the duration of the input signal. Either on applying or removing an input voltage.
Remote Terminal Unit (RTU)	The time functions are disabled. The output follows the appropriate input of the remote device. The input of this channel is transferred to the appropriate output of the remote device. For this mode of operation, two modules have to be connected with a crossover cable or an appropriate transmission link.

Time range ' ms '	100 .. 2000 milliseconds	In steps of 100 ms
Time range ' s '	1 .. 120 seconds	In steps of 1 s
Time range ' m '	1 .. 120 minutes	In steps of 1 min
Time range ' h '	1 .. 100 hours	In steps of 1 h

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